

DSA Cheatsheet

Arrays & Strings

Declaration: `int arr[10];` | `vector<int> v(n);`

Traversal: `for (int i : arr)` or `for (int i = 0; i < n; i++)`

Patterns: Sliding Window, Prefix Sum, Two Pointers

Prefix Sum: `prefix[i] = prefix[i-1] + arr[i];`

Two Pointers: `i = 0, j = n-1; while(i < j) { ... }`

Sorting Algorithms

Bubble: $O(n^2)$, Insertion: $O(n^2)$, Merge: $O(n \log n)$, Quick: $O(n \log n)$

In-place Quick Sort:

```
void qs(int a[], int l, int r) {
    if (l >= r) return;
    int p = a[r], i = l;
    for (int j = l; j < r; j++) if (a[j] <= p) swap(a[i++], a[j]);
    swap(a[i], a[r]); qs(a, l, i-1); qs(a, i+1, r);
}
```

Trees

Inorder: left -> root -> right

Preorder: root -> left -> right

Postorder: left -> right -> root

Height: $\max(\text{height}(l), \text{height}(r)) + 1$

BST: Left < Root < Right, operations $O(\log n)$

Hash Maps & Sets

`unordered_map<int,int> m; unordered_set<int> s;`

Insert/Search $O(1)$ avg. Frequency: `for (int x : arr) m[x]++;`

Stacks & Queues

Stack: `stack<int> s; (LIFO)`

Queue: `queue<int> q; (FIFO)`

Min Stack: `push(val, min_so_far)`

Recursion & Backtracking

```
void backtrack(vector<int>& sol) {
    if (done) output;
    for (...) if (valid) { sol.push_back(...); backtrack(sol); sol.pop_back(); }
}
```

Dynamic Programming

Steps: define `dp[i]`, recurrence, base case

Fibonacci:

`dp[0]=0; dp[1]=1; for(i=2;i<=n;i++) dp[i]=dp[i-1]+dp[i-2];`

Graphs

Adjacency List: `vector<vector<int>> g(n);`

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DFS:

```
void dfs(int u) { vis[u] = 1; for (int v : g[u]) if (!vis[v]) dfs(v); }
```

BFS, Dijkstra (PQ), MST, Topo Sort

Searching

Binary Search:

```
int bs(vector<int>& a, int t) {  
    int l=0, r=a.size()-1;  
    while(l<=r) { int m=(l+r)/2;  
        if(a[m]==t) return m;  
        else if(a[m]<t) l=m+1; else r=m-1; }  
    return -1;  
}
```

Time Complexities

Array: Insert $O(1)$, Search $O(n)$

HashMap: Insert/Search $O(1)$ avg

BST: $O(\log n)$, Heap: Insert/Delete $O(\log n)$